Installation Instructions

CZ-Series

Compact force sensor with flexible installation options for rolls without shaft

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2 Safety instructions

All safety related regulations, local codes and instructions that appear in the manual or on equipment must be observed to ensure personal safety and to prevent damage to the equipment connected to it. If equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

Do not stress the equipment over the specification limits neither during assembly nor operation. To do so can be potentially harmful to persons or equipment in the event of a fault to the equipment.

2.1 Presentation of safety information

The following safety symbols appear in this manual.

2.1.1 Danger that could result in minor or moderate injuries

Danger, warning, caution

Failure to follow wiring instructions in this manual may result in equipment damage or personal injury.

2.1.2 Note regarding proper function

Note

Note regarding proper operation
Simplification of operation
Ensuring function

2.2 General safety information

The force sensors may not be stressed over the specification limits neither during assembly nor operation. The unit’s overload protection value may not be exceeded.

The attachment points for the force sensor on the machine frame must be properly designed. The bearings need to be appropriately mounted.

For proper installation and operation, follow the electrical wiring diagram and instructions in this manual.
3 Product information

3.1 Product description

The CZ-Series force sensor offers compact dimensions and flexible installation options, and are designed for the measurement of tension on continuous material processing lines where idler rolls with integrated bearings without shaft are utilized. The product can be supplied with a Pilot or without a Pilot at the back the unit. In addition, flexible mounting options include the ability to install the unit utilizing either four fasteners from the front or a single fastener from the rear. The included dowel pin can also be incorporated between force measuring bearing and the machine frame to ensure proper unit orientation. For installations where a Pillow Block mount is required the optional bracket can be utilized. The shaft journal of 25 mm diameter accepts standard bearings.

3.2 Functional description

The CZ-Series force measuring sensor combines the bearing seat and the force sensor within the same housing, thus minimizing the required installation space. The substantial overload protection translates to eliminated / minimized calibration issues due to machine upset conditions. The design includes dual bending beams, and this serves to eliminate the load specific influence of torque. The movement of the bending beams, which is proportional to the applied force, is detected by strain gauges arranged in a full bridge circuit and then converted into an electrical signal. This simple measurement principle delivers precise results even with low material tension and small web wrap angles. The Red Point, as located on the sensor body, should be aligned with the direction of the resultant force due to web tension.

3.3 Scope of delivery

Included in scope of delivery

- force sensor, straight connector (female), clip ring,
- installation option PH: 4 pcs. DIN912 M6 x 40,
- installation option FL: dowel pin

Options

- H14 right-angle connector in scope of supply, replaces straight connector
- H16 temperature range up to 120°C (248°F)
- H21 electrical connection with PG gland with 5 m (16 ft.) cable, replaces connector
- H31 for vacuum applications to 1E-7 hPa, 1E-5 Torr, temperature range up to 120°C (248°F)
- H32 vacuum to 1E-7 hPa, 1E-5 Torr, up to 150°C (302°F), with pg-gland and 5 m (16 ft.) cable
- H33 temperature range up to 150°C (302°F), with pg-gland and 5 m (16 ft.) cable
- PH Flange mount with 4 screws, pilot hole for centering
- FL Flat face of force sensor, without shoulder, single screw mount, with dowel pin
**Accessories**

Installation bracket, prefabricated cable (specify length) with connector (straight or right-angle)

### 3.4 Order code

**Figure 1: order code**

![Order Code Diagram](Datasheet_CZ_series.indd)
4 Installation

Force sensors are defined as “partly completed machinery” according to the Directives 2006/42/EC, article 2. In order to assure a proper functionality of the parts and assure the essential safety requirements of operators working with it, the following conditions for the assembly must be met:

- The force sensor may not be stressed over the specification limits neither during assembly nor operation. The unit’s overload protection value may not be exceeded.

- The mounting points for the force sensor on the machine frame must be properly designed. The bearings need to be appropriately mounted.

- For proper installation and operation, follow the electrical wiring diagram and instructions in this manual.

4.1 Installation options

The force sensors of the CZ-series can be installed in two different ways.

- **Screw down on contact surface**
  
  The force sensor should only be bolted down where it has contact to the machine frame.

- **PH - Flansch mit Zentrierschulter**
  
  *PH - Flange with pilot hole for centering*

- **FL - Flach mit Zentrierstift**
  
  *FL - Flat with dowel pin*

![Figure 2: contact surface](C_BA_Manual.ai)
4.1.1 PH Pilot mount

Figure 3: Pilot mount

Figure 4: dimension machine frame for PH mount
4.1.2 Flat mount

Figure 5: Flat mount

4.1.3 Installation bracket CA203.MB (accessory)

Figure 6: dimension machine frame for FL mount

Figure 7: installation bracket CA203.MB

Flansch kann durch lösen der beiden M12 Schrauben um 180° verdreht werden.
Flange part can be flipped 180° by loosening the two M12 screws.
4.2 Electrical connections

Connection between the Force Measuring Rollers and machine controller is realized by means of a 5-pole cable with a cross-section of 0.25mm². The cable must be installed separate from power lines.

<table>
<thead>
<tr>
<th>Pin</th>
<th>DE</th>
<th>EN</th>
<th>IEC 60757</th>
</tr>
</thead>
<tbody>
<tr>
<td>3</td>
<td>Speisung +</td>
<td>Excitation +</td>
<td>XX</td>
</tr>
<tr>
<td>4</td>
<td>Signal -</td>
<td>Signal -</td>
<td>XX</td>
</tr>
<tr>
<td>2</td>
<td>Speisung -</td>
<td>Excitation -</td>
<td>XX</td>
</tr>
<tr>
<td>1</td>
<td>Signal +</td>
<td>Signal +</td>
<td>XX</td>
</tr>
<tr>
<td>5</td>
<td>nicht angeschl.</td>
<td>not connected</td>
<td></td>
</tr>
</tbody>
</table>

**Figure 8: pin assignment M12**

*Pin assignment, top view male connector*

*Polbild, Draufsicht Stift-/ Steckerseite*

*Figure 8: pin assignment M12*

*Pin AssignmentSENSorkabel_Farben_Stecker.ai*
5 Technical data

<table>
<thead>
<tr>
<th>Technical data</th>
<th>Value</th>
</tr>
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<tbody>
<tr>
<td>Sensitivity</td>
<td>1.8 mV/V</td>
</tr>
<tr>
<td>Tolerance of sensitivity</td>
<td>&lt;± 0.5 %</td>
</tr>
<tr>
<td>Accuracy class</td>
<td>±0.5% of nominal force rating</td>
</tr>
<tr>
<td>Temperature coefficient</td>
<td>±0.1%/10K</td>
</tr>
<tr>
<td>Temperature range</td>
<td>-10 to +60°C</td>
</tr>
<tr>
<td>Input resistance</td>
<td>350Ω</td>
</tr>
<tr>
<td>Excitation voltage</td>
<td>1 to 12 VDC</td>
</tr>
<tr>
<td>Overload protection</td>
<td>10 times nominal force</td>
</tr>
<tr>
<td>Material</td>
<td>Stainless steel</td>
</tr>
<tr>
<td>Protection class</td>
<td>IP42</td>
</tr>
<tr>
<td>Electrical connection</td>
<td>Male receptacle, flange mounting, M14x1, 5-pole</td>
</tr>
<tr>
<td>Measuring range</td>
<td>30:1</td>
</tr>
</tbody>
</table>

Table 1: technical data
5.1 Dimensions

Figure 9: Dimensions